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Presented by

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Application of Neural Networks in sound Recognition

Introduction

- Problem: Automatic sound recognition during sleep
- Acoustic properties of snoring
- \blacktriangleright The human sound production process

Signal processing

- Signal pre-processing
- Speech analysis and feature detection

Sound recognition using neural networks

- Topology and characteristics of neural networks
- Learning method for sound recognition

Results

Introduction: Problem: Automatic sound recognition during sleep



Automatic sound recognition and determination of:

- Snore
- Artefacts (cough, harrumps, noises, swallowing)

Side conditions:

- Sound recognition during respiration
- Application of pressure sensor in respirator
 - Limited sample rate

Introduction: Acoustic properties of snoring



Introduction: The human sound production process



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Signal processing: Signal pre-processing

Sound recognition system Recognized sound s(t) Pre-Feature Speech-Training, processing analysis extraction Classification Signal pre-processing Μ W(n) Ν $S_{VtW}(n)$ $s_{Vt}(n)$ **s**(t) s(n) $s_{v}(n)$ A/D-Frame-Pre-Windowing blocking converter emphasis $S_{VtW}(n) = W(n) S_{Vt}(n)$ FIR-Filter 1. order Frame blocking of N samples W(n) - Basis short term analysis - Spectral flattening Separation of adjacent - Reduce influence of frames by M Samples N Sample limited precision - Smooth spectral transitions Minimize leakage effect

Hamming window

$$W(n) = 0.54 - 0.46 \cos\left(\frac{2\pi n}{N-1}\right)$$

 $0 \le n \le N-1$

Signal processing: Speech analysis

Sound recognition system



Linear Predictive Coding (LPC)				
Model	Prediction	Error minimization		

$$s(n) = \sum_{i=1}^{p} a_i s(n-i) + Gq(n)$$
$$S(z) = \left[\frac{1}{1 - \sum_{i=1}^{p} a_i z^{-i}}\right] GQ(z)$$

S(z) = GV(z) Q(z)

$$V(z) = \frac{1}{A(z)}$$

$$\widetilde{s}(n) = \sum_{i=1}^{p} a_i s(n-i)$$
 $e = s(n) - \widetilde{s}(n)$

$$E = \sum_{m=1}^{N-1} \left[s(m) - \sum_{i=1}^{p} a_i \ s(m-i) \right]^2 \longrightarrow \min$$

$$\frac{\partial E}{\partial a_i} = 0 \qquad i = 1, 2, \cdots, p$$

$$\underline{\Phi}_{yy} \cdot \underline{a} = \underline{\varphi}_{yy}$$

Predictor coefficients a_i per short term analysis window

Signal processing: Feature detection



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- Results
- Summary and Conclusion

Sound recognition using neural networks Topology of neural networks

Sound recognition system **Recognized** sound Topology of neural networks Neuron model Human neuron **D**edrites Cell body General neuron Input Output Axon a \underline{w} Rx1l x ln 1 x R 1×1 $a = f(\underline{w} \underline{p} + b)$ 1h 1 R 1×1 Inputs (features) Bias R b \succ human brain: 10¹¹ neurons Transfer function Input vector p $> 10^4$ connections (synapses) per neuron Weight vector a Output W

Sound recognition using neural networks Topology and characteristics of neural networks (feed forward)

Neural network with B layers



Charakteristics of neural networks

- > Approximation of non-linear functions
- Robust classification of unknown signals
- Easy train process
- Combination of different knowledge sources
 - >Acoustic, lexical, pragmatic features, ...

- Pattern recognition and completion
- Data based modelling and prediction
- Contoller design and optimisation
- Sensor fusion
- Automatic sound recognition

Sound recognition using neural networks Learning method for sound recognition

Moment gradient method with adaptive learning rate

	NN Output	$\underline{a}^{B} = \underline{f}^{B} \{ \underline{W} \}$	$^{B}\underline{f}^{B-1} \{ \cdots [\underline{W}^{2}]$	$2 f^{1} (\underline{W}^{1} \underline{p} + \underline{k})$	$(\underline{b}^{1}) + \underline{b}^{2}] \cdots$	$+\underline{b}^{B}$
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Ģ	Gradient method > Training with known Input/Output Data		p	Input vector
		➤ Calculation of error function		Weight matrix
		$ = k \begin{bmatrix} B \\ B \end{bmatrix} = \begin{bmatrix} B \\ B \end{bmatrix} = \begin{bmatrix} T \\ B \end{bmatrix} = \begin{bmatrix} B \\ B \end{bmatrix} = \begin{bmatrix} B \\ B \end{bmatrix} = \begin{bmatrix} T \\ B \end{bmatrix} = \begin{bmatrix} B \\ B \end{bmatrix} = \begin{bmatrix} T \\ B \end{bmatrix} =$	<u>b</u>	Bias vector
		$E^{\kappa} = \left[\underline{a}^{\mathcal{S}}_{Soll}(k) - \underline{a}^{\mathcal{S}}(k)\right] \left[\underline{a}^{\mathcal{S}}_{Soll}(k) - \underline{a}^{\mathcal{S}}(k)\right]$	£	Transfer functions
			<u>a</u>	Output vector
	Weight update	➤ Weight update based on:	ζ	Momentum
		➢ Error function	α	Learning rate
		\blacktriangleright Applied momentum ζ and learning rate α	EE	E Perform. Index
			Q^{7}	Number of
		$\underline{W}^{r}(k) = \underline{W}^{r}(k-1) + \Delta \underline{W}^{r}(k) \qquad \underline{b}^{r}(k) = \underline{b}^{r}(k-1) + \Delta \underline{b}^{r}(k)$		Learningdata
	Learning rate	> Learning rate adaptation after training loop with all training data		
	adaptation	based on perfomance Index		
		$EE^{k} = \sum_{j=1}^{Q_{T}} E^{k} \left[\underline{a}^{B}_{Soll,j}(k), \underline{a}^{B}(k) \right]^{T} \left[\underline{a}^{B}_{Soll,j}(k) - \underline{a}^{B}(k) \right]$		
		<i>j</i> =1		
	Stop Learning	> Stop training with minimum performance index EE		

Trained

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Results: Methods

Feature vector

$$\underline{\rho} = \begin{bmatrix} G & c_{xx}^{L}(1,t) & \cdots & c_{xx}^{L}(6,t) & \dot{c}_{xx}^{L}(1,t) & \cdots & \dot{c}_{xx}^{L}(3,t) \end{bmatrix}^{T}$$

	Neural network]
Topology	 > 3 networks with 2 and 3 layers: > 10-2, 10-15-2, 10-5-2 > 10 input, 2 outputs > Transfer functions: Log-Sigmoid f(n) = 1/(1+e⁻ⁿ) 	f Transfer functions n Input vector of f α Learning rate ζ Momentum η Learning threshold l Stopp threshold
Learning	▶ 20 snores $\underline{a}_{Soll,snore}^{B} = \begin{bmatrix} 1 & 0 \end{bmatrix}^{T}$ $\alpha(0) = 0,01$ $\zeta = 0,9$ $\eta = 1,04$ $l = 5$ ▶ 1-4 Reference persons	
Test	 20 snores 160 artefacts 	

Results: Correct recognition

94 % Laver 10-2 Correct recognition in 92 Layer 10-15-2 90 Layer 10-5-2 88 86 84 82 80 1 2 ³ Number reference persons

Snoring



Mixed sound



<u>Snoring</u>

- Increased detection rate ~ number reference
 - person for 3 layer NN

Artefacts

- Decreased detection rate ~ number reference person for 3 layer NN
- ➢ Better detection with 2 layer NN

Artefacts

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Summary

Introduction in human sound signal processing

- ➤ Modelling
- Signal pre-processing
- ➢ Speech analysis and feature detection

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Example: Automatic sound recognition during sleep

- ➤ Topology, learning
- Classification results

Conclusion

Computer power consuming recognition task

Realtime feature detection + classification (parallel computing)

Neural networks are reliable in sound recognition

- Easy implementation and training
- Robust classification of unknown sound signals
- Difficult optimization

Broader application of neural networks with falling computer prizes is expected.